

Introduction to dispersion rheology

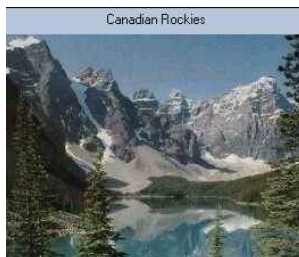
Contents

- 1. Solids, liquids and butter**
- 2. Elastic and Shear deformations**
- 3. Non-Newtonian behaviour**
- 4. Stress relaxation and elastic recoil**
- 5. Dynamic viscosity measurements**
- 6. Viscosity of dispersions of spherical particles**

Introduction to dispersion rheology

States of matter

• Solids



- keep their shape
- do not flow

• Liquids



- flow
- take the shape of the (solid) container

? butter, yoghurt, ketchup...

liquids ? or solids ?



- **Solids → elastic deformation
returns to its original shape**

- **Liquids flow if forces are applied
on it → viscous flow**

- **Question of time scale and magnitude of exerted forces**
 - ◆ **water : small forces during very short times
→ elastic deformation**

 - ◆ **mountains : large forces during very long times
→ flow**

? Intermediate times and forces ?

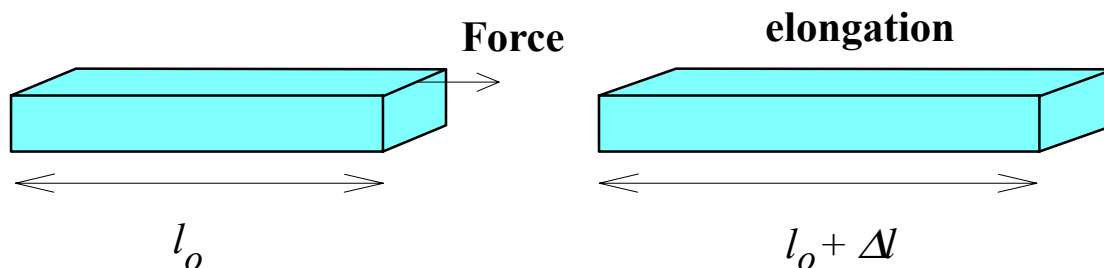
→ Viscoelasticity

Dispersions

In general viscoelastic “liquid like” behaviour

→ **flows on time scales short compared
to human lifetime**

Elastic deformation



Strain $\frac{\Delta l}{l_0} = \varepsilon$

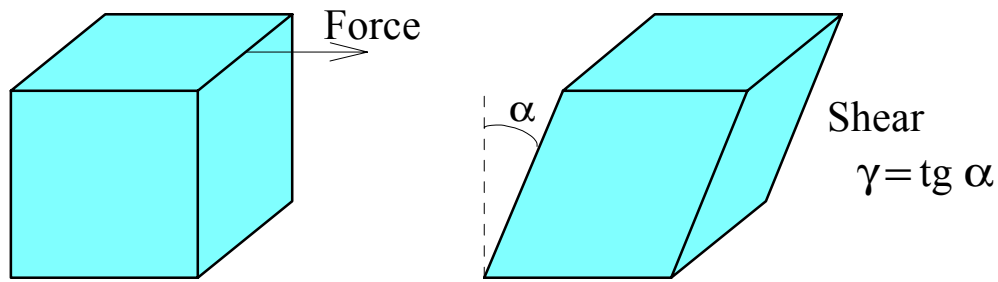
Stress $T = \text{Force} / \text{unit area}$

→ **linear relation stress / strain (Hooke's law)**

$$T = E\varepsilon$$

Young's modulus

Shear deformation



Shear deformation with constant speed on liquid → flow

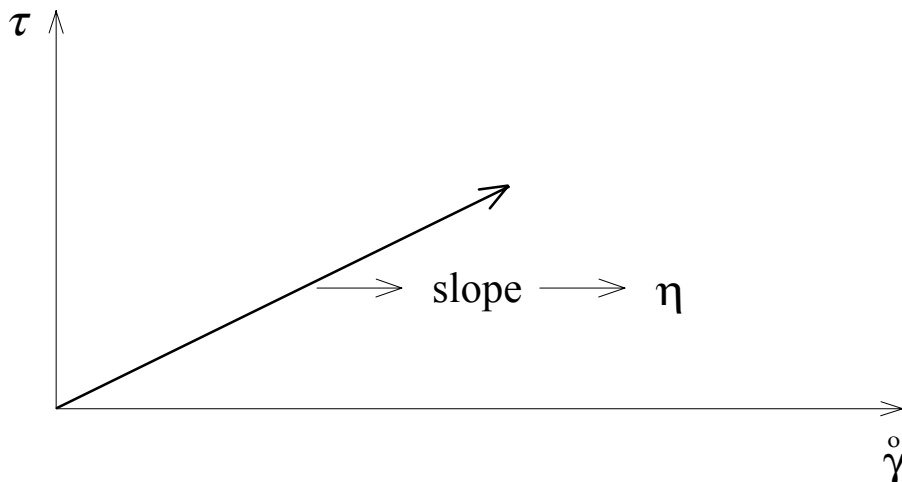
→ **Shear rate** $\dot{\gamma}$

Shear stress $\tau = \text{force} / \text{unit area}$

→ **Linear relation shear stress / shear rate**
(Newtonian viscosity)

$$\tau = \eta \dot{\gamma}$$

(Newtonian) viscosity



Non-Newtonian behaviour

- **Most dispersions (also blood)**
 η dependent on the shear rate

→ viscosity is a material function
 $\eta = \eta(\dot{\gamma})$

Reason : complexity of the micro structure of the system

Structural changes due to exerted forces
 → changes in viscosity

⇒ rheology can be used to learn about the
 microstructure of dispersions

- **More general**

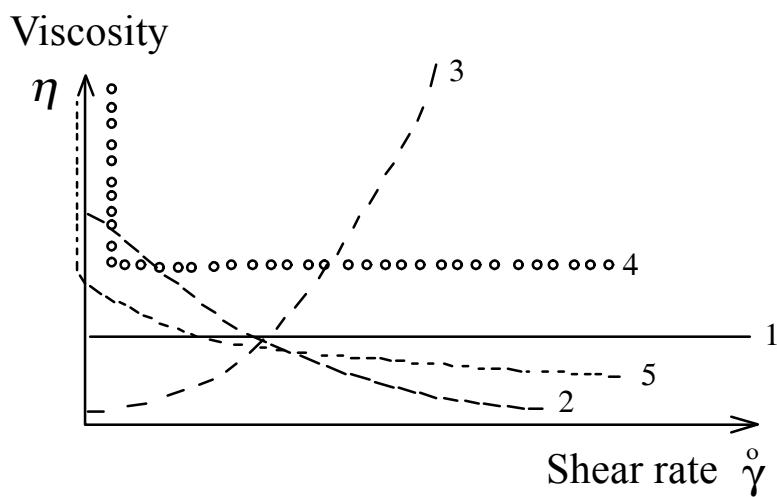
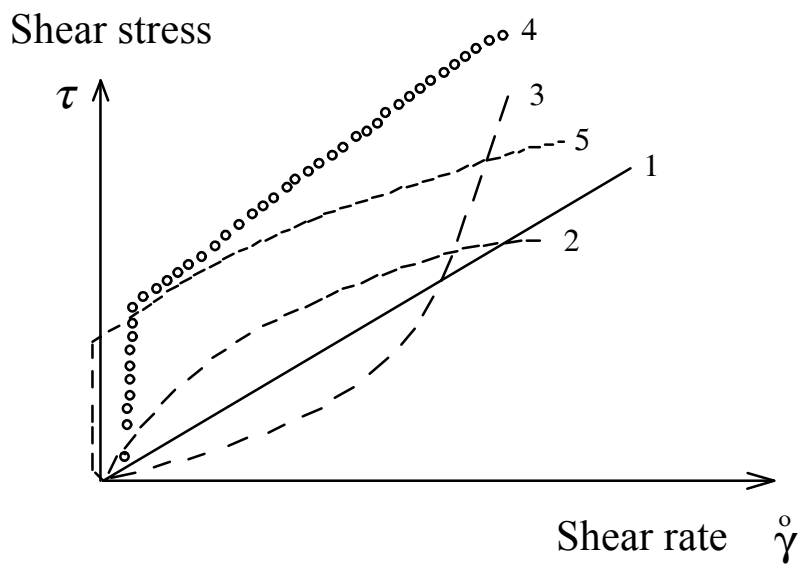
$$\eta = \eta(\dot{\gamma}, time)$$

→ structural changes

require in general some time

→ η is not a material function

Shear dependent behaviour

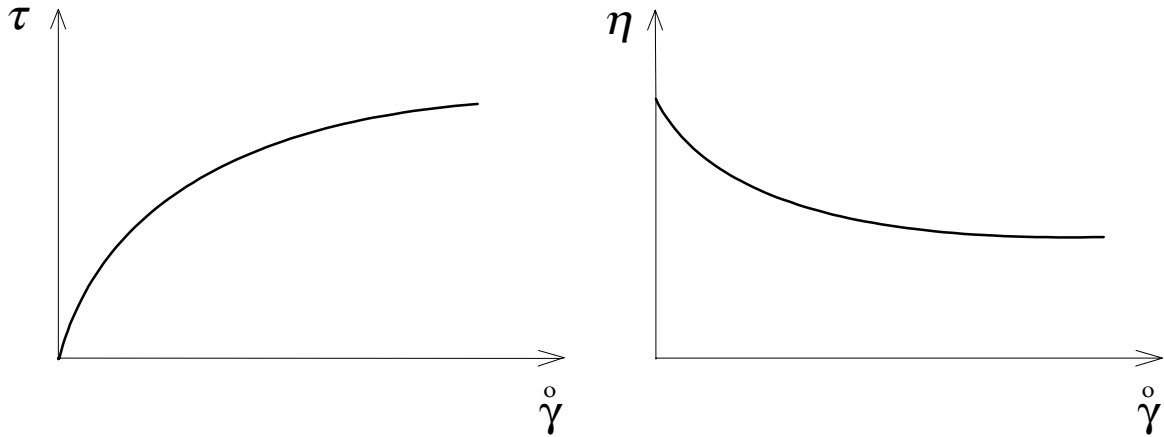


How to define viscosity

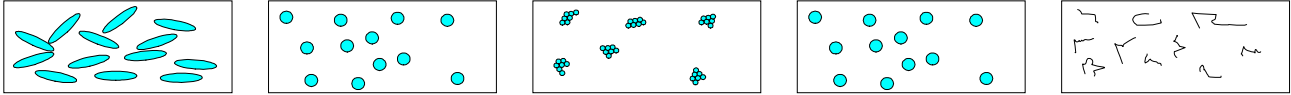
a) **slope viscosity** $\eta(\dot{\gamma}) = d\tau / d\dot{\gamma}$

b) **apparent viscosity** $\eta_a(\dot{\gamma}) = \tau / \dot{\gamma}$

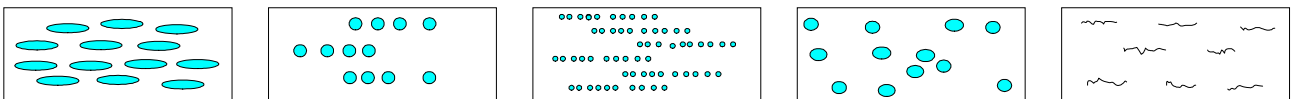
Shear thinning behaviour



Systems at rest



Flowing systems



orientation

ordering

desaggregation

deformation

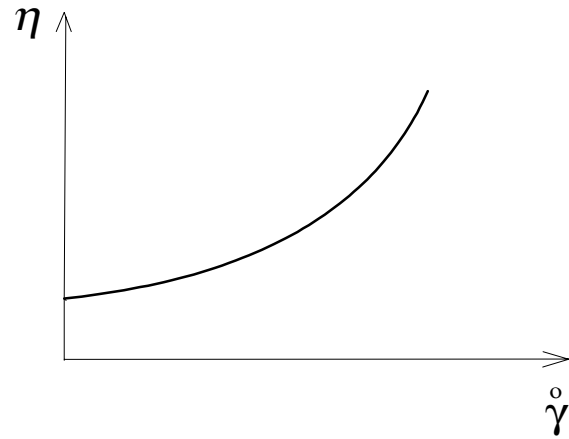
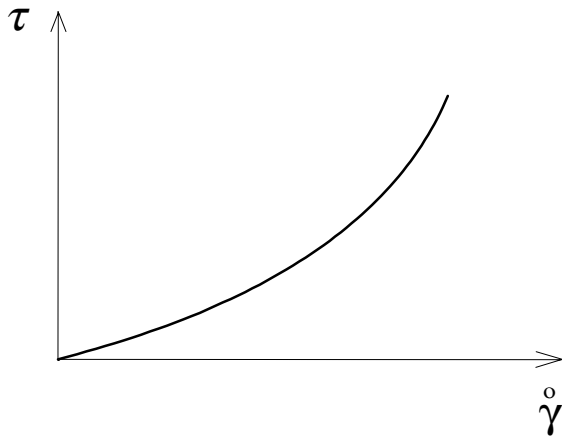
elongation

Empirical equations

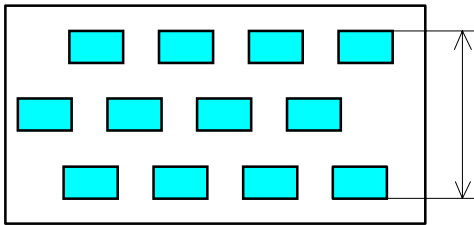
$$\tau = k\dot{\gamma}^n$$

$$n < 1$$

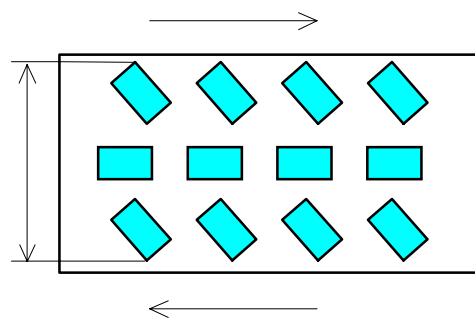
Shear thickening



System at rest



System in motion

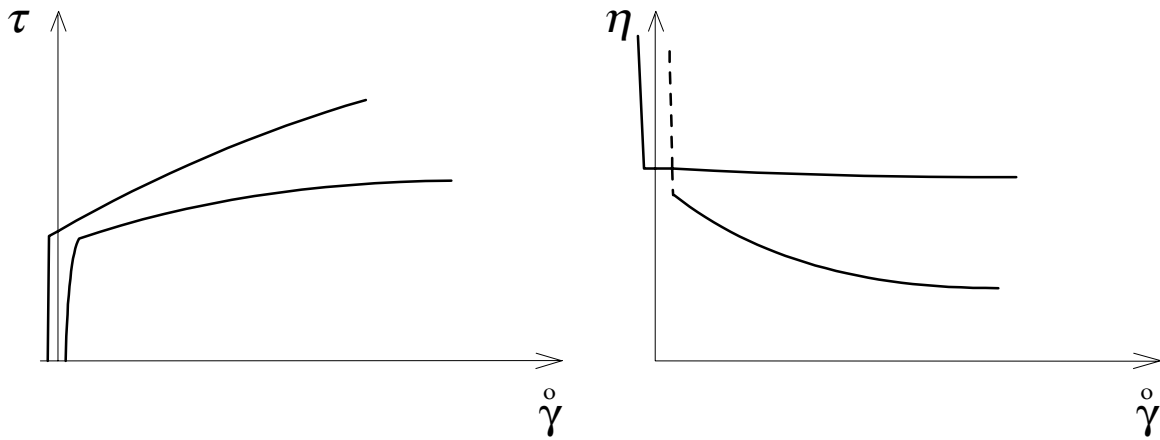


Empirical law

$$\tau = k\dot{\gamma}^n$$

$n > 1$

Materials with yield value



1 Bingham flow

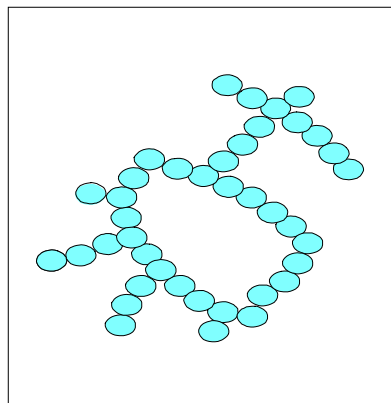
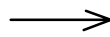
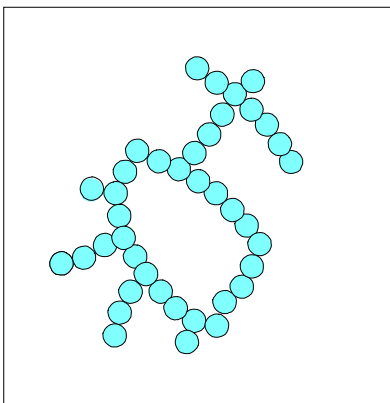
$$\tau = \tau_0 + k\dot{\gamma}$$

yield value

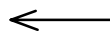
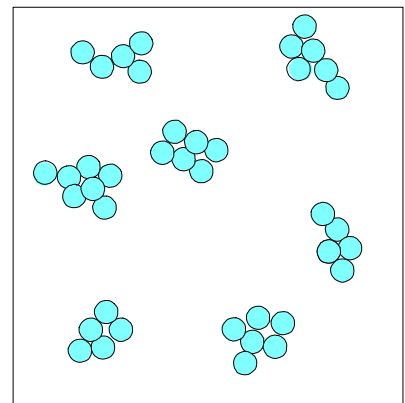
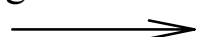
2 Hershel-Bulkly

$$\tau = \tau_0 + k\dot{\gamma}^n$$

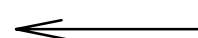
at rest



large deformation

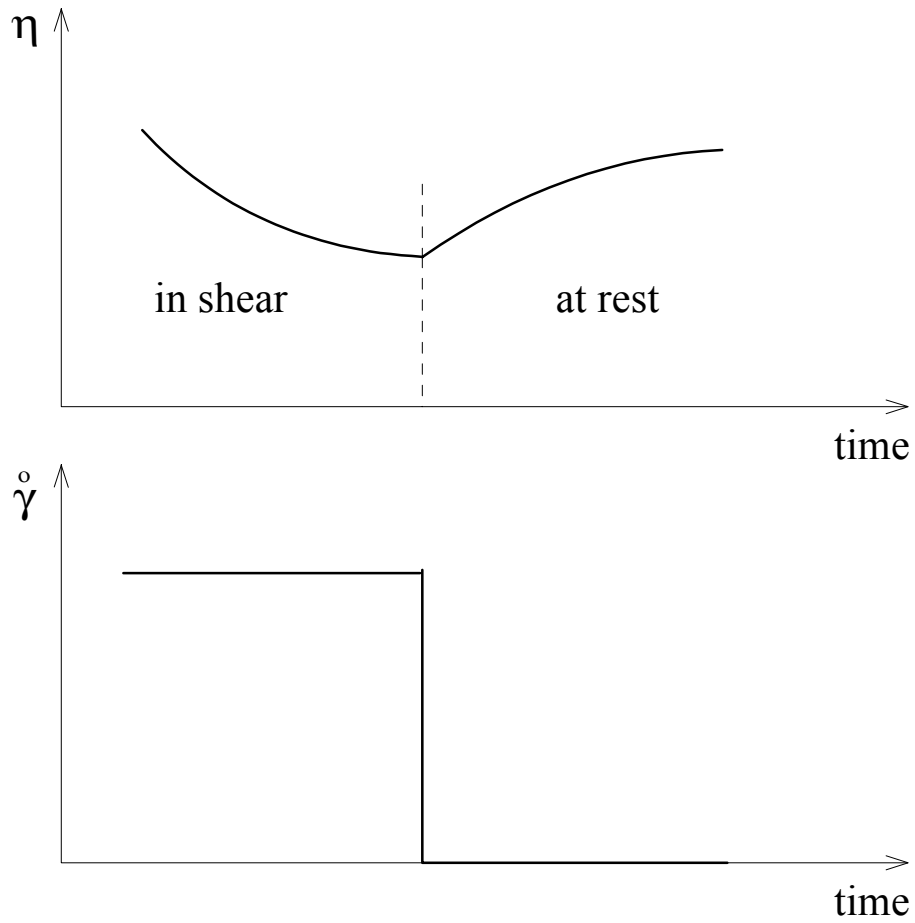


small deformation

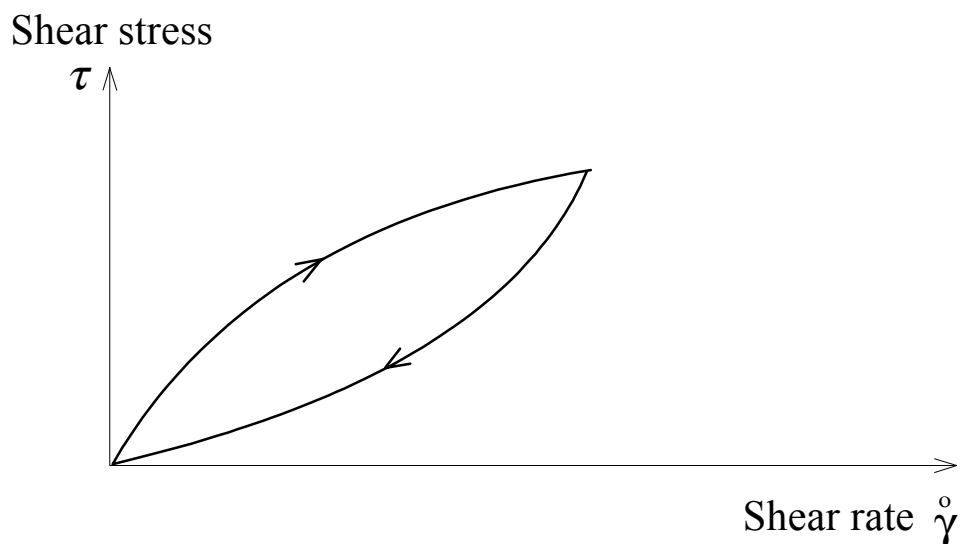


Time dependent behaviour

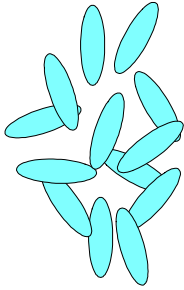
Thixotropy (“memory effects”)



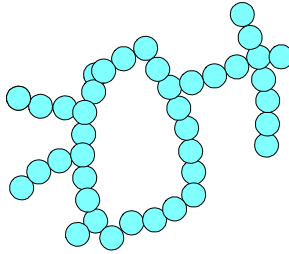
Thixotropic hysteresis



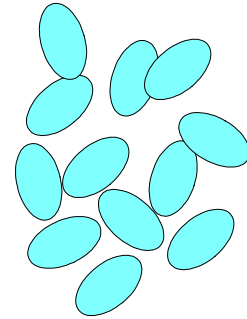
Reason → mesh-work structure



bars

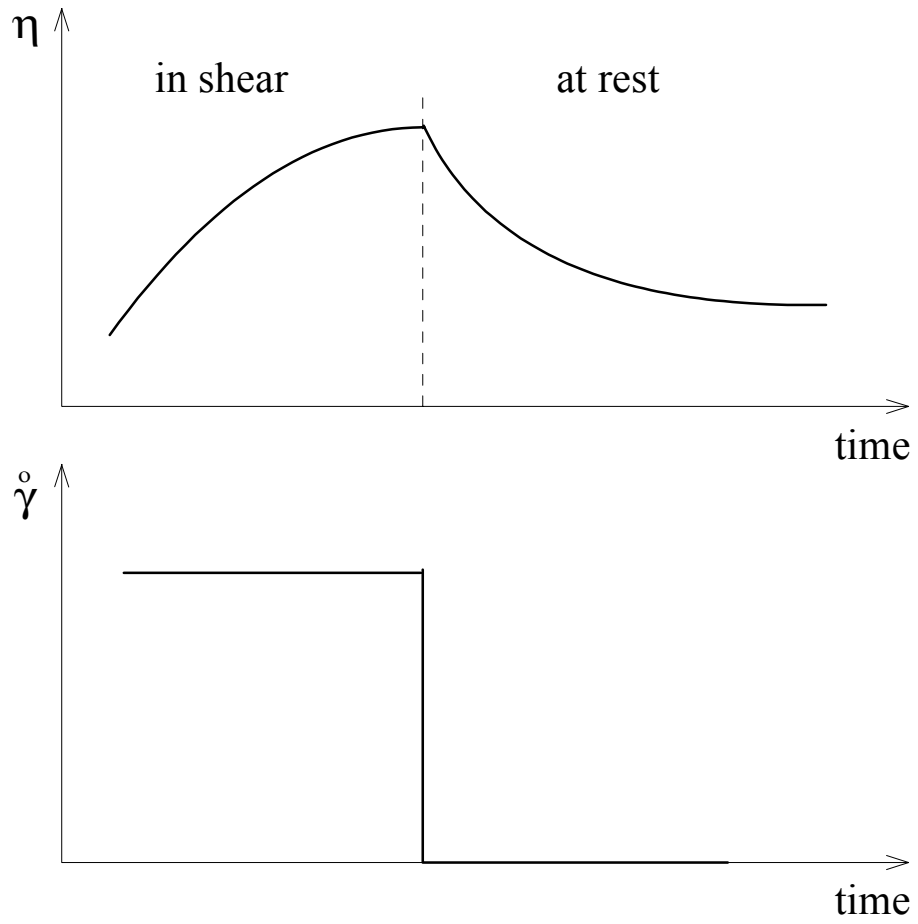


balls



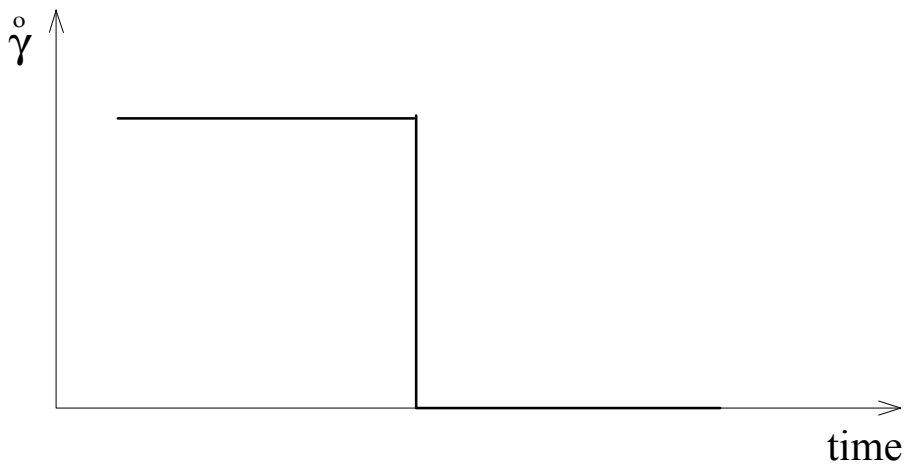
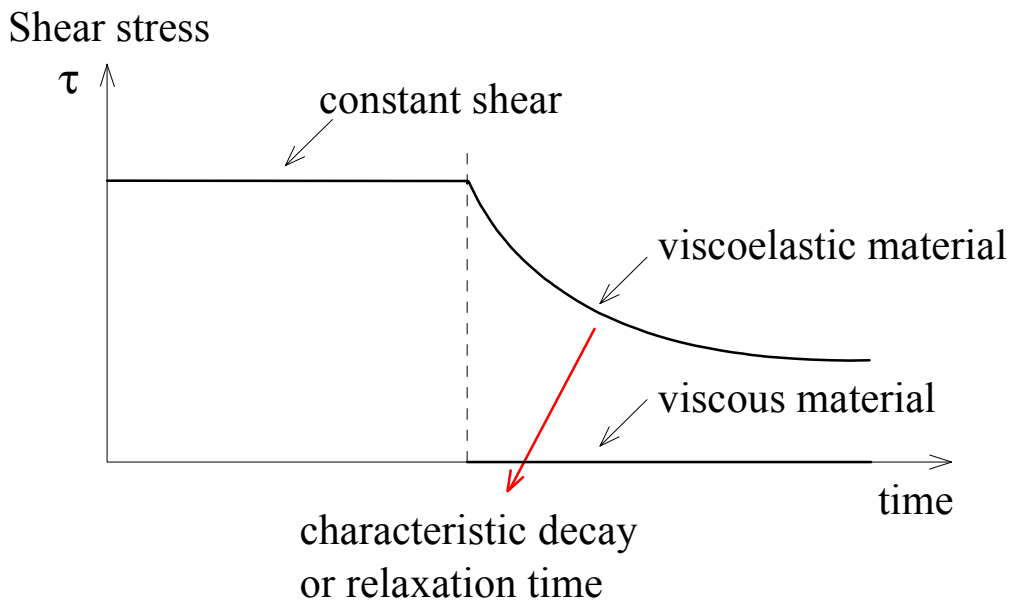
plates

Rheopecty

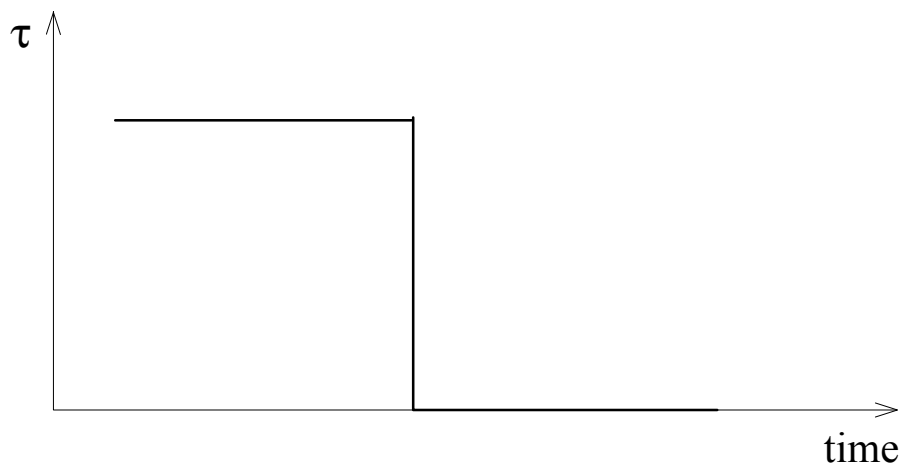
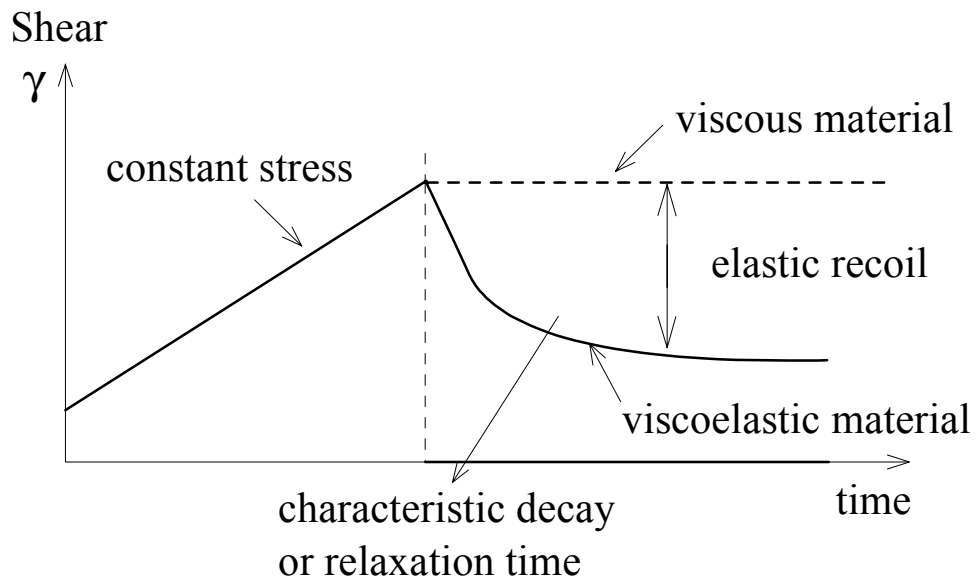


Viscoelastic materials

Stress relaxation



Elastic recoil



Deborah number

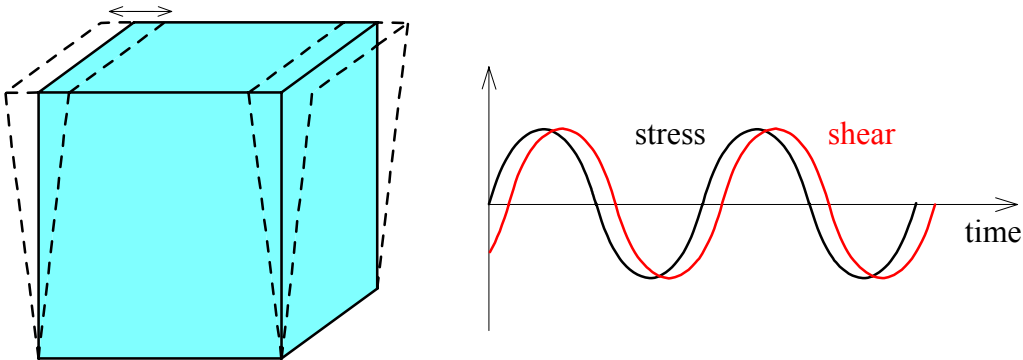
$$Deborah = \frac{\textit{relaxation time}}{\textit{observation time}}$$

Deborah $\ll 1$ \rightarrow viscous liquid

Deborah $\gg 1$ \rightarrow elastic solid

Viscoelasticity \rightarrow Deborah ~ 1

Dynamic viscosity measurements



Shear

$$\gamma(t) = \gamma_0 \sin \omega t$$

Stress

$$\tau(t) = \gamma_0 G' \sin \omega t + \gamma_0 G'' \cos \omega t$$

elastic term
in phase
 G' storage modulus

viscous term
 90° out of phase
 G'' loss modulus

- **Elastic material** $\rightarrow G'' = 0$
- **Viscous material** $\rightarrow G' = 0$

$$\tau(t) = \tau_0 \sin(\omega t + \delta)$$

 **loss angle**

$$G' = \frac{\tau_0}{\gamma_0} \cos \delta \quad G'' = \frac{\tau_0}{\gamma_0} \sin \delta$$

$$\frac{G''}{G'} = \tan \delta$$

$\delta = 0 \rightarrow$ **elastic**

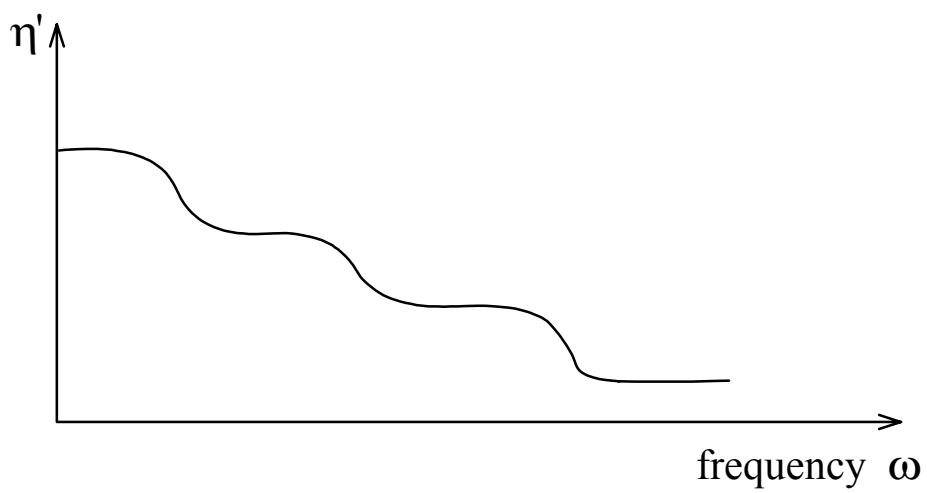
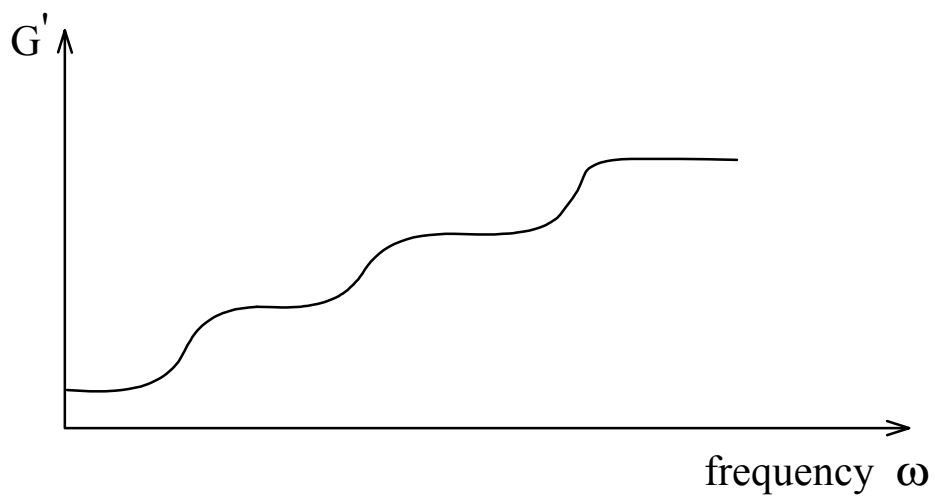
$\delta = 90^\circ \rightarrow$ **viscous**

$\delta \sim 45^\circ \rightarrow$ **viscoelastic**

Dynamic or complex viscosity η^*

$$\eta^* = \eta' + i \eta'' \quad (i^2 = -1)$$

$$\eta' = G'' / \omega \quad \eta'' = G' / \omega$$



Viscosity of dispersions of spherical particles

- Newtonian behaviour for volume fractions $\phi \leq 0.1$
- $0.1 \leq \phi \leq 0.5$ shear thinning
- $\phi \geq 0.5$ shear thickening
- Low ϕ (≤ 0.1) \rightarrow Einstein equation

$$\eta_r = \frac{\eta_s}{\eta_0} = 1 + \frac{5}{2} \phi$$

relative viscosity viscosity of medium

- Slightly higher ϕ (≤ 0.15)

$$\eta_r = 1 + k_1 \phi + k_2 \phi^2$$

2.5 6.2 – 5.2

- High ϕ (≤ 0.15)

→ empirical equations

- Krieger-Dougherty equation

$$\eta_r = [1 + k_p \phi]^{-2.5/k_p}$$

$1/k_p = \phi_\infty$ → closest packing volume fraction

- Mooney equation

$$\eta_r = [\exp 2.5 \phi / (1 + k_p \phi)]$$

